

Motion control

Lexion 23 Plus

BCH servo motors



BCH servo motor range

Presentation

BCH servo motors are synchronous motors.

They are equipped as standard with a high resolution (20-bit) incremental encoder. They are therefore ideal for high performance applications such as material working, machine tools, etc.

The servo motors are available in six flange sizes: 40 mm, 60 mm, 80 mm, 100 mm, 130 mm and 180 mm.

They are available in a version with holding brake (see opposite page).

With the four types of motor inertia available, ranging from ultra low to high inertia, the servo motors can be used in a very wide variety of installations:

- Ultra low inertia:
power between 0.1 kW and 0.4 kW, suitable for electronic equipment and small printing machinery.
- Low inertia:
power between 0.4 kW and 2 kW, suitable for textile and packaging applications.
- Medium inertia:
power between 0.3 kW and 3 kW, suitable for material working and machine tool applications.
- High inertia:
power between 2 kW and 7.5 kW, suitable for metal working and printing applications.

Examples of applications according to motor inertia type:

Type of machine	Inertia			
	Ultra low	Low	Medium	High
Conveyors				
Packaging machines				
Printers				
Loaders/unloaders				
X - Y tables				
Presses				
PCB drilling machines				
Electronic card testers				
Labelling machines				
Knitting and embroidery machines				
Special machines				
Winders/unwinders				

References													
Example:	B	C	H	0	4	0	1	O	0	2	A	1	C
Servo motor BCH = three-phase servo motor	B	C	H	0	4	0	1	O	0	2	A	1	C
Flange size 040 = 40 mm 060 = 60 mm 080 = 80 mm 100 = 100 mm 130 = 130 mm 180 = 180 mm	B	C	H	0	4	0	1	O	0	2	A	1	C
Number of motor stages 1 = 1 stage (all flange sizes) 2 = 2 stages (with 60, 80, 100, 130 and 180 mm flanges) 3 = 3 stages (with 130 and 180 mm flanges) 4 = 4 stages (with 130 and 180 mm flanges) 5 = 5 stages (with 180 mm flange)	B	C	H	0	4	0	1	O	0	2	A	1	C
Speed type M = slow (1000/1500 rpm), (with 130 and 180 mm flanges) N = medium (2500 rpm), (with 130 and 180 mm flanges) O = fast (3000 rpm), (with 40, 60, 80 and 100 mm flanges)	B	C	H	0	4	0	1	O	0	2	A	1	C
Shaft end 0 = smooth, IP 40 degree of protection 1 = keyed, IP 40 degree of protection 2 = smooth, IP 65 degree of protection 3 = keyed, IP 65 degree of protection	B	C	H	0	4	0	1	O	0	2	A	1	C
Integrated encoder 2 = 20-bit high resolution incremental encoder	B	C	H	0	4	0	1	O	0	2	A	1	C
Holding brake A = without brake F = with brake	B	C	H	0	4	0	1	O	0	2	A	1	C
Connection 1 = flying leads (for BCH040...080 servo motors) or round connector (for BCH100...180 servo motors)	B	C	H	0	4	0	1	O	0	2	A	1	C
Type of mounting C = mechanical	B	C	H	0	4	0	1	O	0	2	A	1	C

Characteristics													
Servo motors	Without holding brake						With holding brake						
	W x H x D (1)			Weight			W x H x D (1)			Weight			
	mm			kg			mm			kg			
BCH0401	40 x 40 x 100.6			0.500			40 x 40 x 136.6			0.800			
BCH0601	60 x 60 x 105.5			1.200			60 x 60 x 141.6			1.500			
BCH0602	60 x 60 x 130.7			1.600			60 x 60 x 166.8			2.000			
BCH0801	80 x 80 x 112.3			2.100			80 x 80 x 152.8			2.900			
BCH0802	80 x 80 x 138.3			3.000			80 x 80 x 178			3.800			
BCH1001	100 x 100 x 153.5			4.300			100 x 100 x 192.5			4.700			
BCH1002	100 x 100 x 199			6.200			100 x 100 x 226			7.200			
BCH1301	130 x 130 x 147.5			6.800			130 x 130 x 183.5			8.200			
BCH1302	130 x 130 x 147.5			7.000			130 x 130 x 183.5			8.400			
BCH1303M	130 x 130 x 163.5			7.500			130 x 130 x 198			8.900			
BCH1303N	130 x 130 x 167.5			7.500			130 x 130 x 202			8.900			
BCH1304	130 x 130 x 187.5			7.800			130 x 130 x 216			9.200			
BCH1801	180 x 180 x 169			13.500			180 x 180 x 203.1			17.500			
BCH1802	180 x 180 x 202.1			18.500			180 x 180 x 235.3			22.500			
BCH1803N	180 x 180 x 202.1			18.500			180 x 180 x 235.3			22.500			
BCH1803M	180 x 180 x 235.3			23.500			180 x 180 x 279.3			29.000			
BCH1804M	180 x 180 x 279.7			30.500			180 x 180 x 311.7			36.000			
BCH1805M	180 x 180 x 342			37.000			180 x 180 x 376.1			53.000			

(1) D: dimensions of the casing (excluding shaft end)

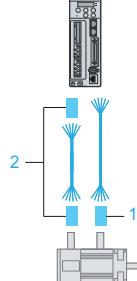
Motion control

Lexion 23 Plus

BCH servo motors

Connection accessories

Connection accessories				
Designation	Description	Reference	Weight kg	
Set of 3 terminal blocks	1 terminal block for power supply 1 terminal block for motor power supply 1 terminal block for braking resistor For mounting on drive side	VW3 M4 121	0.500	
Connector for I/O interface	For mounting on drive side	VW3 M4 112	0.050	
Screw terminal block	For I/O interface For mounting on drive side	VW3 M4 113	0.020	
RS 232/USB converter	Equipped with: ■ One USB connector ■ One RJ 45 connector	VW3 M8 131	0.300	
Connection cable				
Designation	Description	Cable length	Reference	Weight kg
Connection cable for VW3 M8 131 converter	Equipped with an RJ 45 connector at each end. To connect the VW3 M8 131 converter to the servo drive.	2 m	490 NTW 00002	–
Connectors for power cable				
Description	For servo motor	Item no.	Reference	Weight kg
Connector for motor without holding brake	BCH 0401O•2•1C BCH 0601O•2•1C BCH 0602O•2•1C BCH 0801O•2•1C BCH 0802O•2•1C	1	VW3 M5 111	0.030
Connector for motor with holding brake	BCH 06010•2F1C BCH 06020•2F1C BCH 08010•2F1C BCH 08020•2F1C	1	VW3 M5 112	0.030
Round connectors for motor with or without holding brake	BCH 1001O•2•1C BCH 1002O•2•1C BCH 1301Me•2•1C BCH 1301N•2•1C BCH 1302Me•2•1C BCH 1302N•2•1C BCH 1303Me•2•1C BCH 1304N•2•1C BCH 1801N•2•1C BCH 1802Me•2•1C BCH 1802N•2•1C BCH 1803Me•2•1C BCH 1803N•2•1C BCH 1804Me•2•1C BCH 1805Me•2•1C	1	VW3 M5 121 VW3 M5 131	0.180 0.180
Connector for holding brake	BCH 1804Me•2F1C BCH 1805M•2F1C	1	VW3 M5 141	0.300
			VW3 M7 151	0.500
Connectors for encoder cable				
Description	For servo motor	Item no.	Reference	Weight kg
Connector for motor with connection via stripped cable	BCH 0401O•2•1C BCH 0601O•2•1C BCH 0602O•2•1C BCH 0801O•2•1C BCH 0802O•2•1C	2	VW3 M8 121	0.800
Connector for motor equipped with a round connector	BCH 1001O•2•1C BCH 1002O•2•1C BCH 1301Me•2•1C BCH 1301N•2•1C BCH 1302Me•2•1C BCH 1302N•2•1C BCH 1303Me•2•1C BCH 1303N•2•1C BCH 1304N•2•1C BCH 1801N•2•1C BCH 1802Me•2•1C BCH 1802N•2•1C BCH 1803Me•2•1C BCH 1803N•2•1C BCH 1804Me•2•1C BCH 1805Me•2•1C	2	VW3 M8 122	0.800



Motion control

Lexion 23 Plus

BCH servo motors

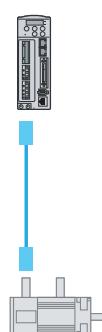
Connection accessories



Connection components (continued)

Power cordsets

Description	From servo motor	To servo drive	Composition	Length of cable	Reference	Weight
				m		kg
Cordsets equipped with a plastic connector (servo motor end) and one end with flying leads (servo drive end). Without holding brake	BCH0401O•2A1C	LXM23•U01M3X	4 x 0.82 mm ²	3	VW3 M5 111R30	0.200
	BCH0601O•2A1C	LXM23•U02M3X		5	VW3 M5 111R50	0.350
	BCH0602O•2A1C	LXM23•U04M3X				
	BCH0801O•2A1C	LXM23•U04M3X				
	BCH0802O•2A1C	LXM23•U07M3X				
Cordsets equipped with a plastic connector (servo motor end) and one end with flying leads (servo drive end). With holding brake	BCH0401O•2F1C	LXM23•U01M3X	6 x 0.82 mm ²	3	VW3 M5 112R30	0.200
	BCH0601O•2F1C	LXM23•U02M3X		5	VW3 M5 112R50	0.350
	BCH0602O•2F1C	LXM23•U04M3X				
	BCH0801O•2F1C	LXM23•U04M3X				
	BCH0802O•2F1C	LXM23•U07M3X				
Cordsets equipped with a round connector (servo motor end) and one end with flying leads (servo drive end). Without holding brake	BCH1001O•2A1C	LXM23•U10M3X	4 x 1.3 mm ²	3	VW3 M5 121R30	0.350
	BCH1301M•2A1C	LXM23•U04M3X		5	VW3 M5 121R50	0.600
	BCH1301N•2A1C	LXM23•U04M3X				
	BCH1302M•2A1C	LXM23•U07M3X				
	BCH1302N•2A1C	LXM23•U10M3X				
	BCH1303M•2A1C	LXM23•U10M3X				
	BCH1303N•2A1C	LXM23•U15M3X				
	BCH1002O•2A1C	LXM23•U20M3X	4 x 2.1 mm ²	3	VW3 M5 122R30	0.450
	BCH1304N•2A1C	LXM23•U20M3X		5	VW3 M5 122R50	0.750
	BCH1801N•2A1C	LXM23•U20M3X	4 x 3.3 mm ²	3	VW3 M5 123R30	0.760
	BCH1802N•2A1C	LXM23•U30M3X		5	VW3 M5 123R50	1.750
	BCH1802M•2A1C	LXM23•U30M3X				
	BCH1803M•2A1C	LXM23•U45M3X				
	BCH1803N•2A1C	LXM23•U45M3X	4 x 8.4 mm ²	3	VW3 M5 124R30	1.000
				5	VW3 M5 124R50	1.200
Cordsets equipped with a round connector (servo motor end) and one end with flying leads (servo drive end). With holding brake	BCH1001O•2F1C	LXM23•U10M3X	6 x 1.3 mm ²	3	VW3 M5 131R30	0.350
	BCH1301M•2F1C	LXM23•U04M3X		5	VW3 M5 131R50	0.600
	BCH1301N•2F1C	LXM23•U04M3X				
	BCH1302M•2F1C	LXM23•U07M3X				
	BCH1302N•2F1C	LXM23•U10M3X				
	BCH1303M•2F1C	LXM23•U10M3X				
	BCH1303N•2F1C	LXM23•U15M3X				
	BCH1002O•2F1C	LXM23•U20M3X	6 x 2.1 mm ²	3	VW3 M5 132R30	0.750
	BCH1304N•2F1C	LXM23•U20M3X		5	VW3 M5 132R50	1.250
	BCH1801N•2F1C	LXM23•U20M3X	6 x 3.3 mm ²	3	VW3 M5 133R30	0.760
	BCH1802M•2F1C	LXM23•U30M3X		5	VW3 M5 133R50	1.950
	BCH1802N•2F1C	LXM23•U30M3X				
	BCH1803N•2F1C	LXM23•U45M3X				
	BCH1803M•2F1C	LXM23•U45M3X	6 x 8.4 mm ²	3	VW3 M5 134R30	—
				5	VW3 M5 134R50	—



Encoder cordsets

Cordsets equipped with a plastic connector at each end	BCH0401O•2•1C	LXM23•U01M3X	10 x 0.13 mm ²	3	VW3 M8 121R30	1.000
	BCH0601O•2•1C	LXM23•U01M3X		5	VW3 M8 121R50	1.200
	BCH0602O•2•1C	LXM23•U04M3X				
	BCH0801O•2•1C	LXM23•U04M3X				
	BCH0802O•2•1C	LXM23•U07M3X				
Cordsets equipped with a round connector (servo motor end) and a plastic connector (servo drive end)	BCH1001O•2•1C	LXM23•U10M3X	10 x 0.13 mm ²	3	VW3 M8 122R30	1.000
	BCH1002O•2•1C	LXM23•U20M3X		5	VW3 M8 122R50	1.200
	BCH1301M•2•1C	LXM23•U04M3X				
	BCH1301N•2•1C	LXM23•U04M3X				
	BCH1302M•2•1C	LXM23•U07M3X				
	BCH1302N•2•1C	LXM23•U10M3X				
	BCH1303M•2•1C	LXM23•U10M3X				
	BCH1303N•2•1C	LXM23•U15M3X				
	BCH1304N•2•1C	LXM23•U20M3X				
	BCH1801N•2•1C	LXM23•U20M3X				
	BCH1802M•2•1C	LXM23•U30M3X				
	BCH1802N•2•1C	LXM23•U30M3X				
	BCH1803M•2•1C	LXM23•U45M3X				
	BCH1803N•2•1C	LXM23•U45M3X				
	BCH1804M•2•1C	LXM23•U75M3X				
	BCH1805M•2•1C	LXM23•U75M3X				